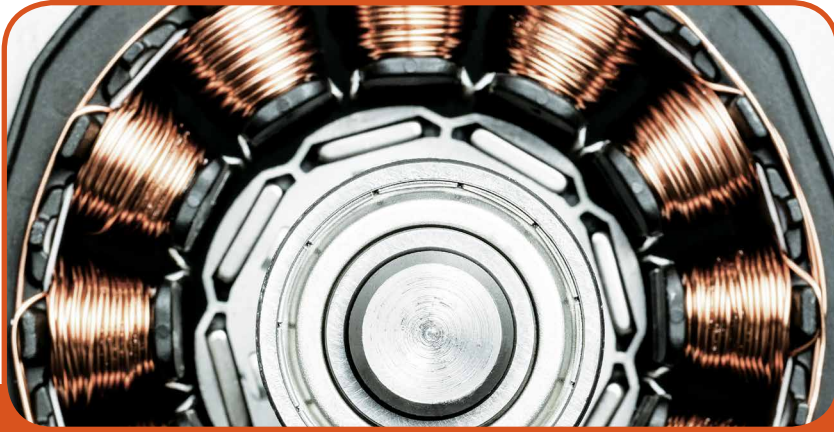




ARM® Cortex®-M4  
MCU family for  
BLDC, PMSM and  
ACIM motor control

## Kinetis KV3x MCU Family

The Kinetis KV3x family of microcontrollers is a high-performance solution for BLDC, PMSM and ACIM motor control applications. Enabled with Kinetis Motor Suite.

### TARGET APPLICATIONS

- ▶ BLDC motors
- ▶ PMSM motors
- ▶ ACIM motors

Built upon the Cortex-M4 core running at 100/120 MHz with DSP and floating point unit, it features dual 16-bit analog-to-digital converters (ADCs) sampling at up to 1.2 mega samples per second (MSPS), multiple motor control timers, 64 to 512 KB of flash memory and a comprehensive enablement suite from proprietary and third-party resources, including reference designs, software libraries and motor configuration tools.

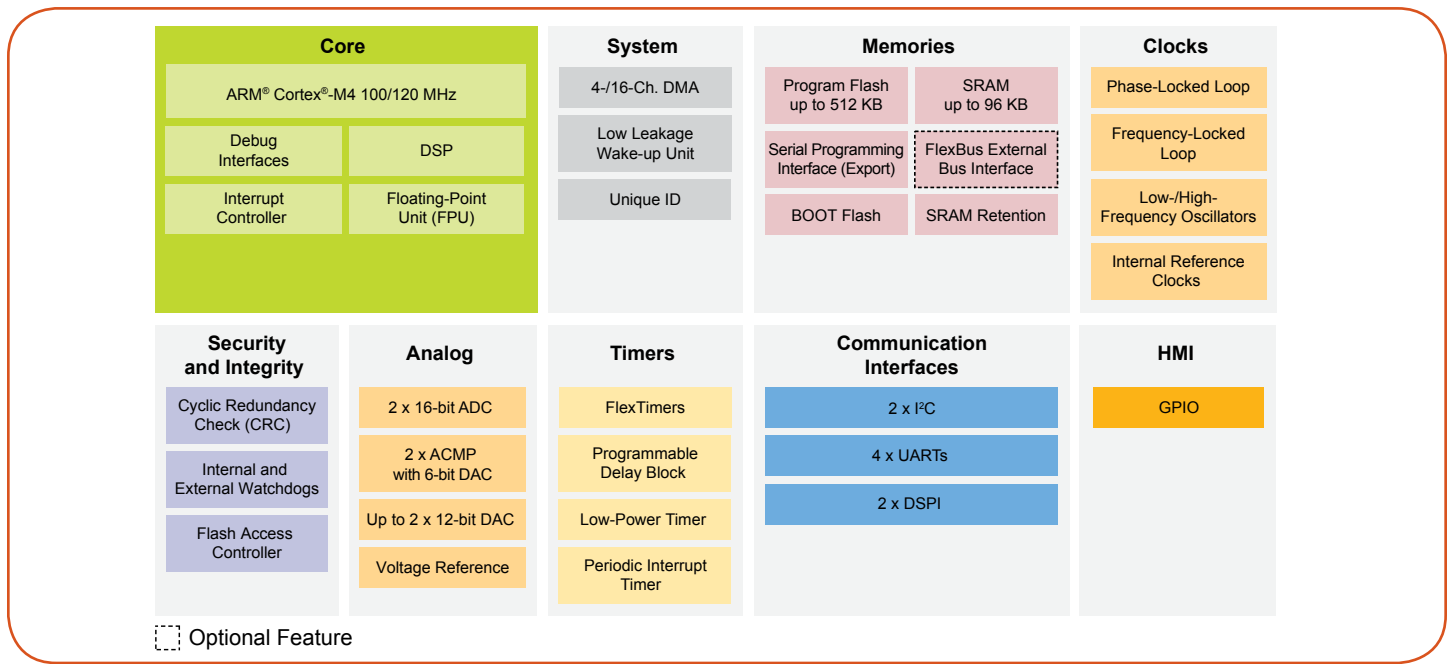
### FEATURES AND BENEFITS

- ▶ 100/120 MHz Cortex-M4 core with DSP and floating point unit—improves performance in math-intensive applications (e.g., processing of sensorless FOC (field oriented control) algorithms)
- ▶ 2x 16-bit ADCs with two capture and hold circuits and up to 1.2 MSPS sample rate—simultaneous measurement of current and voltage phase, reduced jitter on input values improving system accuracy

- ▶ Up to 2 x 8-channel and 2 x 2-channel programmable FlexTimers—high-accuracy PWM generation with integrated power factor correction or speed sensor decoder (incremental decoder/hall sensor)
- ▶ Up to 2 x 12-bit DAC and 2 x ACPMs (analog comparators)—overcurrent and overvoltage fault detection, reduced BOM costs. ADC and ACMP interconnect with PWM and PDB (programmable delay blocks) for real-time hardware control
- ▶ 4- or 16-channel DMA—reduced CPU loading for improved application performance
- ▶ Dual watchdogs—compliance with IEC 60730 safety regulation requirements



## KINETIS KV3x MCU FAMILY BLOCK DIAGRAM



### DEVELOPMENT TOOLS

Kinetis Motor Suite (KMS) is a software solution that enables the rapid configuration of motor drive systems, accelerates development of the final motor drive application while improving overall motor system performance due to its unique SpinTAC™ enabled speed controller. Tuning and optimization is carried out via a simple graphical user interface that enables a developer to easily identify their motor, tune that motor using just one control dial and build a state machine to control the various speed transitions of the motor.

#### HVP-MC3PH

The platform enables development of three-phase PMSM, BLDC and ACIM motor control and power factor correction (PFC) solutions in a safe high-voltage environment.

Compatible with the HVP-KV31F120M controller card, input voltage is 85–240 V AC, with output power of the motor stage up to 1 KW and the ability to drive a 1.2 Hp motor.

#### FRDM-KV31F

An ultra-low-cost development platform for Kinetis KV3x MCUs. The FRDM-KV31F hardware is form-factor compatible with the Arduino™ R3 pin layout, providing a broad range of expansion board options.

Combine this with the FRDM-MC-LVPMSM or FRDM-MC-LVBLDC shields and the FRDM-MC-LVMTR to create a fully-enabled development platform for PMSM or BLDC motor control.

#### TWR-KV31F120M

The Tower System MCU module is a development board that features the KV3x MCU in a 100 LQFP package, integrated OpenSDA debug adapter, and is compatible with the TWR-MC-LV3PH three-phase motor peripheral module.

#### TWR-MC-LV3PH

The TWR-MC-LV3PH low-voltage, three-phase motor control Tower® System peripheral module provides a complete motor control reference design kit for developing BLDC and PMSM motor solutions, it includes a three-phase motor and motor drive circuitry.

#### Integrated Development Environment (IDE), Software Development Kit (SDK) and Config Tools

Kinetis V series MCUs are supported by MCUXpresso Software and Tools (IDE, SDK, Config Tools), as well as, IAR Embedded Workbench® for ARM.

### Reference Designs Built on Embedded Motor Control Libraries

- ▶ Extensive suite of complimentary reference designs for ACIM, BLDC and PMSM motor control built on NXP's Embedded Software libraries and motor configuration tools.
- ▶ Complex real-time control applications
- ▶ Core self-test libraries for simpler IEC 60730 certification

#### FreeMASTER

FreeMASTER is a free and simple, yet highly customizable real-time debug monitor and data visualization tool that enables real-time data access.

#### Motor Control Toolbox

Motor control development toolbox is a comprehensive collection of tools that plug into MATLAB™/Simulink™ design environment to support rapid application development targeting Kinetis KV MCUs.

## KINETIS KV3x MCU FAMILY

| PART NUMBER       | MAX FREQ.<br>(MHz) | PIN<br>COUNT | PACKAGE | FLASH (KB) | SRAM (KB) | KMS | FLEX.BUS | DMA    | PLL or FLL | FLEX TIMERS          | DAC |
|-------------------|--------------------|--------------|---------|------------|-----------|-----|----------|--------|------------|----------------------|-----|
| MKV31F512VLL12    | 120                | 100          | LQFP    | 512        | 96        | NO  | YES      | 16-ch. | PLL        | 2 x 8-ch.; 2 x 2-ch. | 2   |
| MKV31F512VLH12    | 120                | 64           | LQFP    | 512        | 96        | NO  | YES      | 16-ch. | PLL        | 2 x 8-ch.; 2 x 2-ch. | 2   |
| MKV31F512VLL12P   | 120                | 100          | LQFP    | 512        | 96        | YES | YES      | 16-ch. | PLL        | 2 x 8-ch.; 2 x 2-ch. | 2   |
| MKV31F512VLL12Q** | 120                | 100          | LQFP    | 512        | 96        | YES | YES      | 16-ch. | PLL        | 2 x 8-ch.; 2 x 2-ch. | 2   |
| MKV31F256VLL12    | 120                | 100          | LQFP    | 256        | 48        | NO  | NO       | 16-ch. | PLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV31F256VLH12    | 120                | 64           | LQFP    | 256        | 48        | NO  | NO       | 16-ch. | PLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV31F256VLH12P   | 120                | 64           | LQFP    | 256        | 48        | YES | NO       | 16-ch. | PLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV31F128VLL10    | 100                | 100          | LQFP    | 128        | 24        | NO  | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV31F128VLH10    | 100                | 64           | LQFP    | 128        | 24        | NO  | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV31F128VLH10P   | 100                | 64           | LQFP    | 128        | 24        | YES | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV30F128VLH10    | 100                | 64           | LQFP    | 128        | 16        | NO  | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV30F128VLF10    | 100                | 48           | LQFP    | 128        | 16        | NO  | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV30F128VFM10    | 100                | 32           | QFN     | 128        | 16        | NO  | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV30F128VLF10P   | 100                | 48           | LQFP    | 128        | 16        | YES | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV30F64VLH10     | 100                | 64           | LQFP    | 64         | 16        | NO  | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV30F64VLF10     | 100                | 48           | LQFP    | 64         | 16        | NO  | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV30F64VFM10     | 100                | 32           | QFN     | 64         | 16        | NO  | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV30F64VLH10P*   | 100                | 64           | LQFP    | 64         | 16        | YES | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |
| MKV30F64VLF10P*   | 100                | 48           | LQFP    | 64         | 1         | YES | NO       | 4-ch.  | FLL        | 1 x 8-ch.; 2 x 2-ch. | 1   |

\* package your way

\*\* Q suffix indicates KMS enabled ACIM motor device

[www.nxp.com/Kinetis/VSeries](http://www.nxp.com/Kinetis/VSeries)

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